

Distributed Sensor and Cyber-Physical Systems

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Where is Computer Science Research Going?

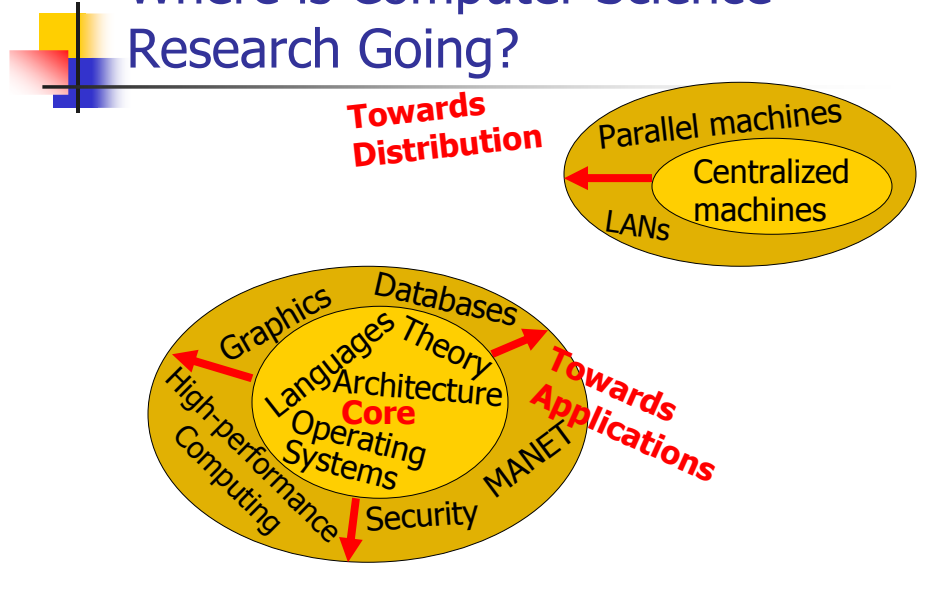


The beginning:

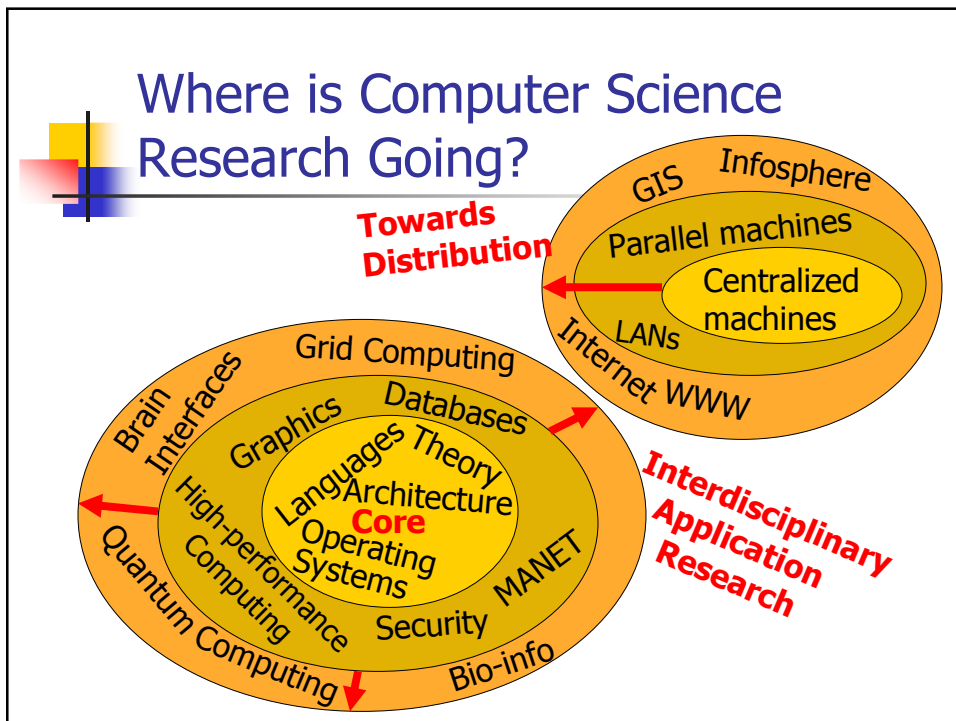
Centralized machines

Languages Theory
Architecture
Core
Operating Systems

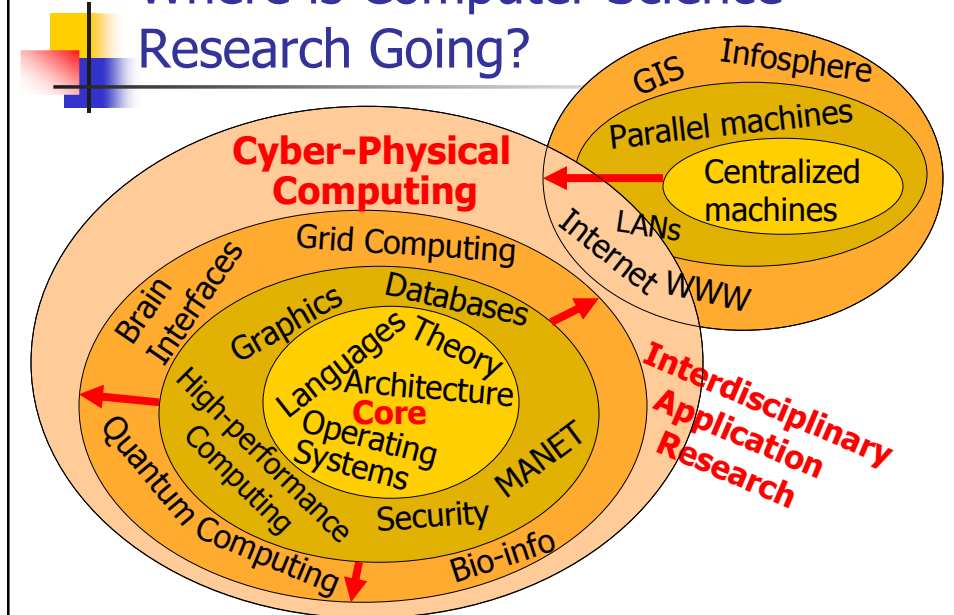
Where is Computer Science Research Going?



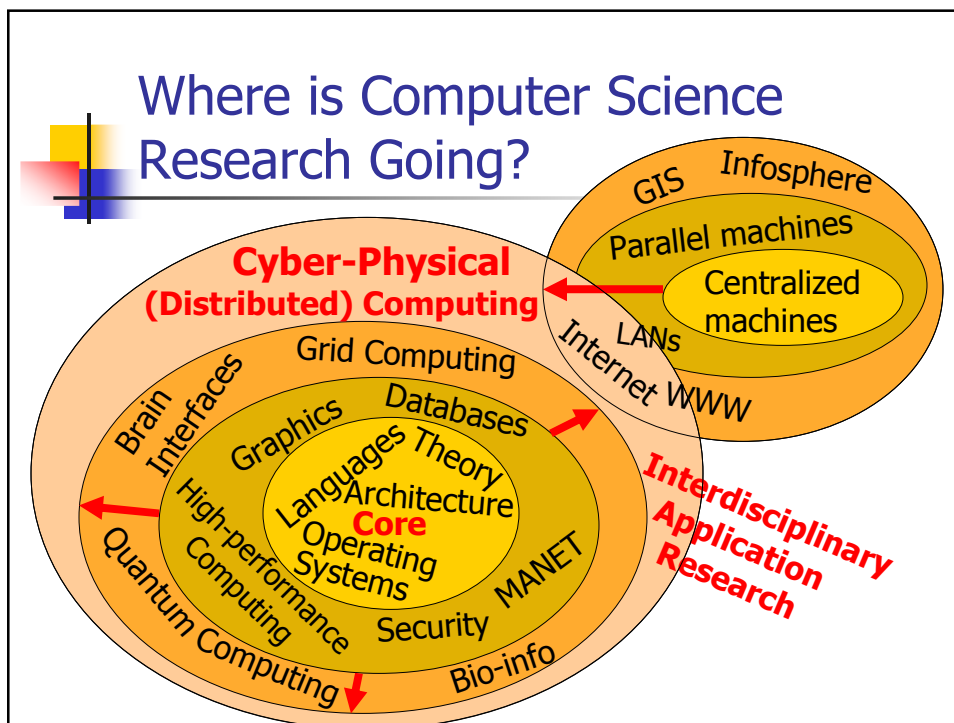
Where is Computer Science Research Going?



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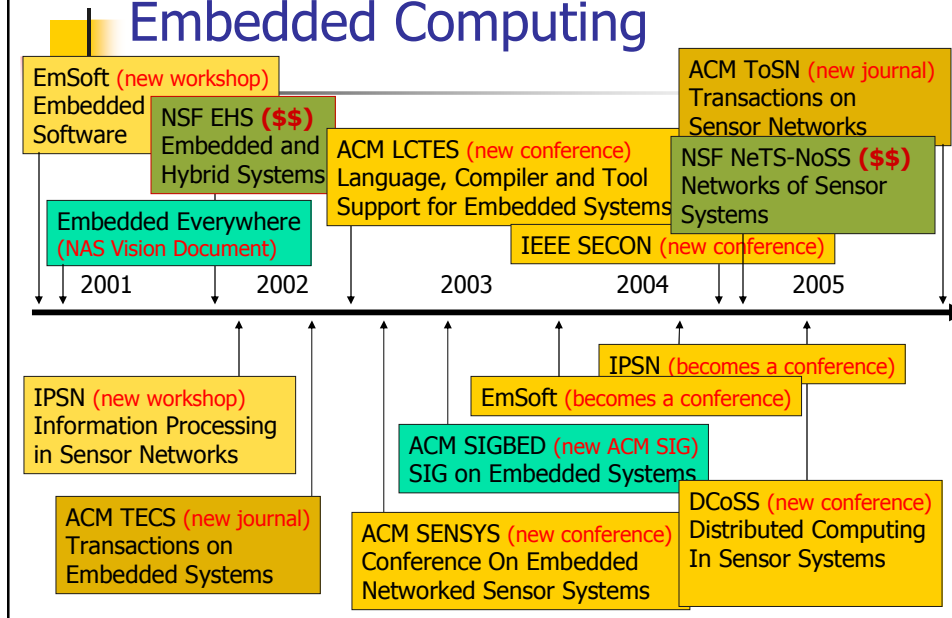
Cyber-Physical Distributed Systems


For example:

In the US, the **Presidential Council of Advisors in Science and Technology** named systems that interact with the physical world the

#1 Research Priority in the US

Expanding Interest in Deeply Embedded Computing





Distributed Cyber-Physical Systems versus Embedded Systems?

- A more holistic/interdisciplinary approach
 - More distribution
 - Less structure
 - Interactions between multiple autonomous domains (privacy and security implications)
 - Increasingly open systems
- Think: Distributed versus parallel computing



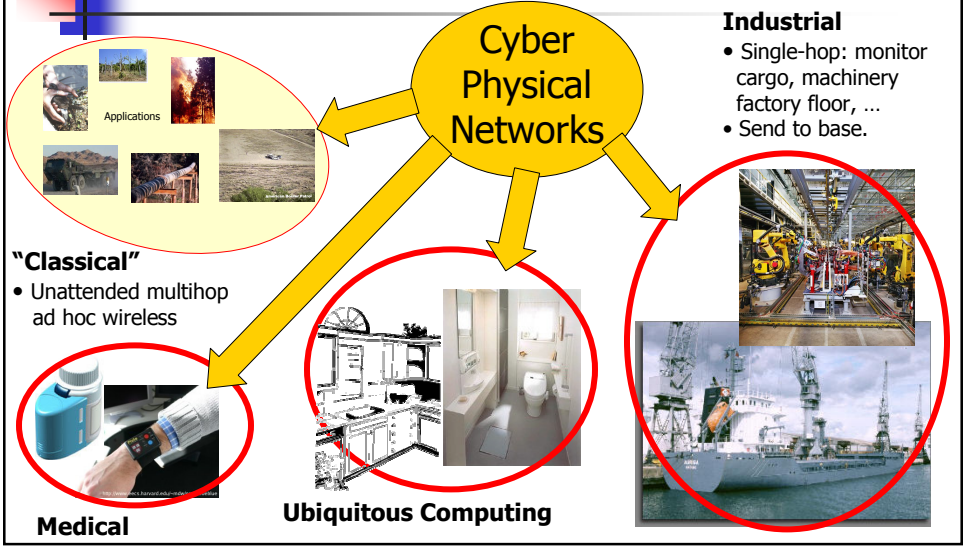
Cyber-Physical Systems

- In 2007 and 2008:
 - PCAST Report on US Competitiveness names CPS as #1 priority
 - RTSS (#1 Real-time conference) adds CPS track
 - IPSN/HSCC/RTAS 2008 Join for CPS Week
 - Several New CPS Workshops
 - High Confidence Cyber-Physical Systems (July 2007)
 - From Embedded Systems to CPS (w/ RTAS 2008)
 - First International Workshop on CPS (w/ ICDCS 2008)
 - ...
 - NSF Initiative to fund CPS track

Publication Counts

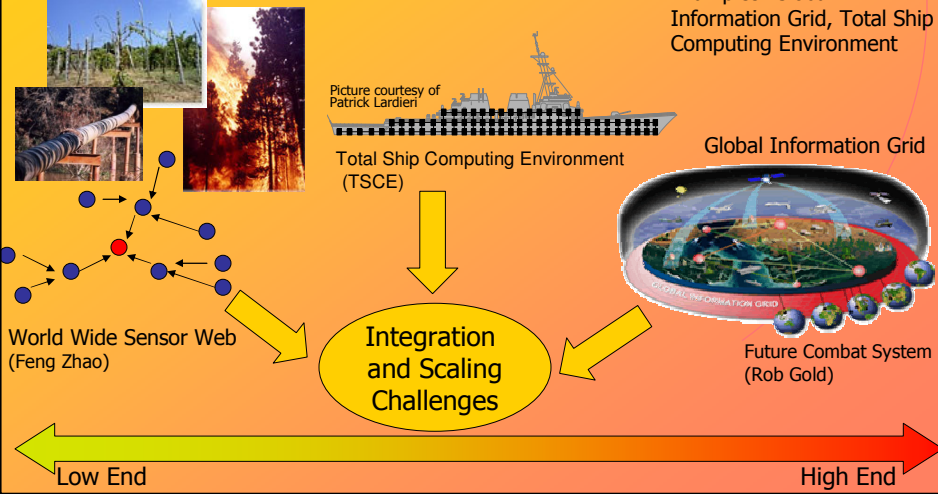
Year	Sensor Networks	Cyber-Physical	Internet	
1997	6			
1998	13		1988	
1999	21		1989	71
2000	39		1990	110
2001	95		1991	132
2002	213		1992	200
2003	609		1993	359
2004	1489		1994	863
2005	2423		1995	1711
2006	3365	1	1996	3954
		4	1997	6207
			1998	6657
			1999	7017
			2000	8831
			2001	10224
			2002	12755

Force #1: Moore's Law (Device proliferation)

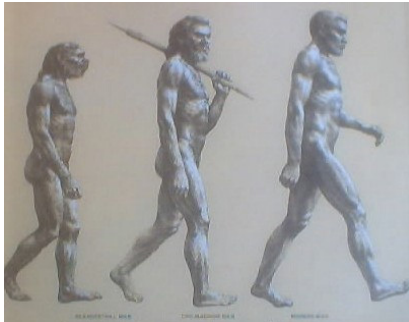


Force #2: Integration at Scale (Isolation has cost!)

- Low end: ubiquitous embedded devices
 - Large-scale networked embedded systems
 - Seamless integration with a physical environment
- High end: complex systems with global integration
 - Examples: Global Information Grid, Total Ship Computing Environment

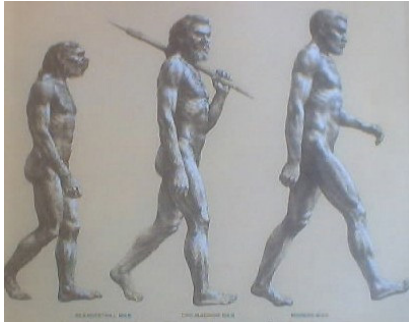


Force #3: Biological Evolution





Force #3: Biological Evolution



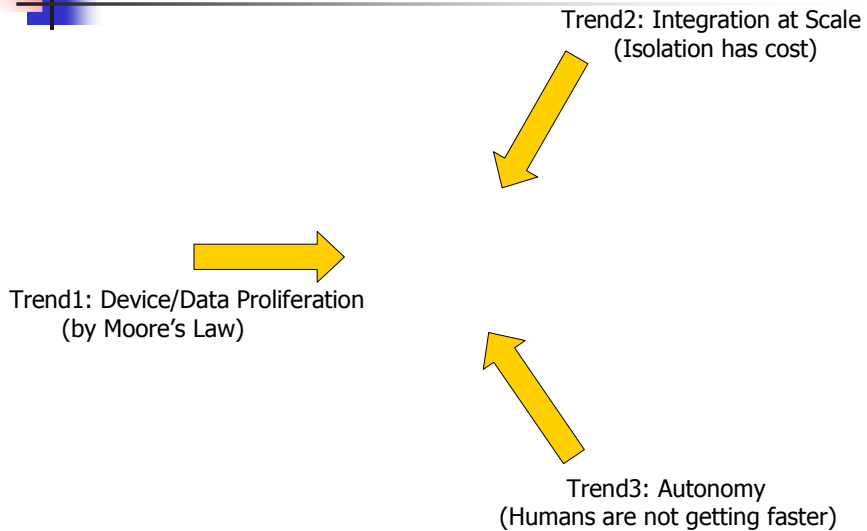
- **It's too slow!**

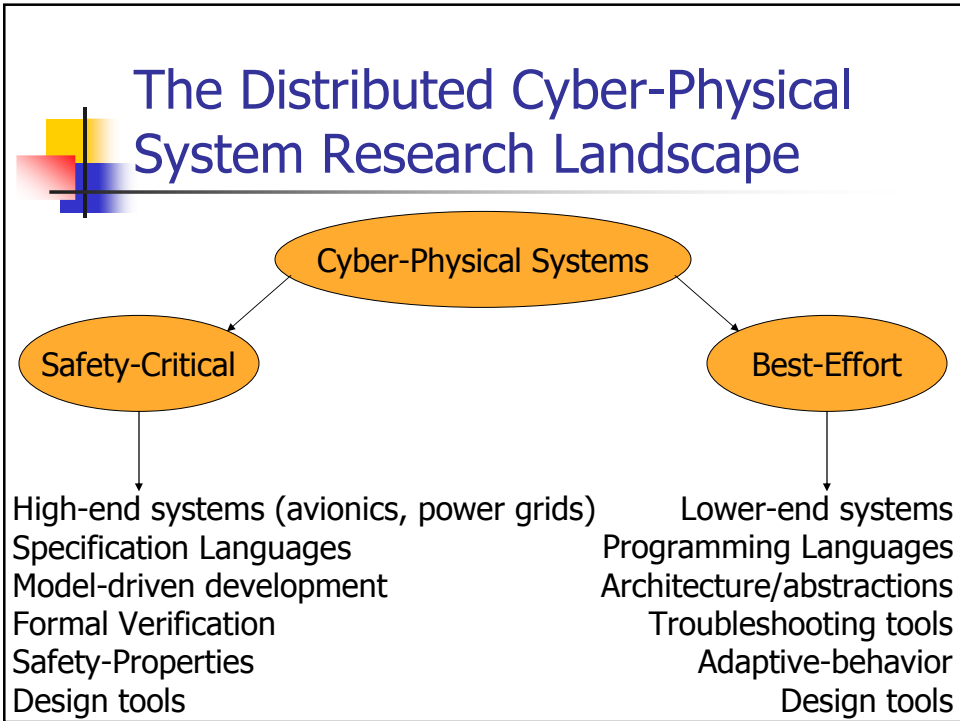
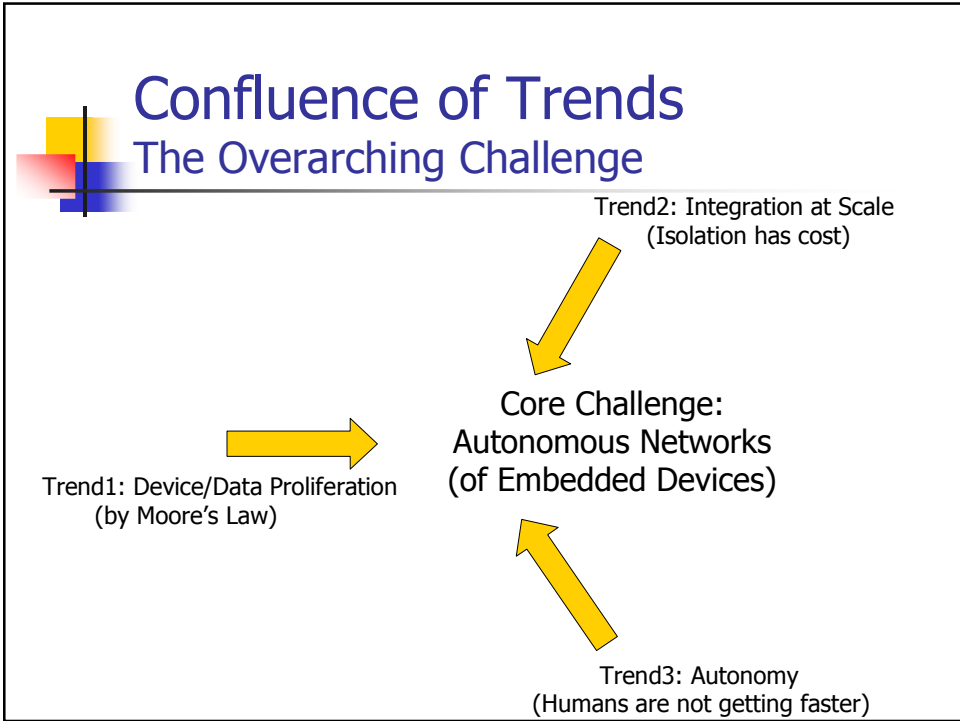
- The exponential proliferation of data sources (afforded by Moore's Law) is **not** matched by a corresponding increase in human ability to consume information!

→ Increasing autonomy (human out of the loop), direct world access



Confluence of Trends The Overarching Challenge







This Class

- **Instructor**
Tarek Abdelzaher, 4126 SC, Tel: (217) 265-6793, e-mail: zaher
- **Lecture Times**
Schedule: Wednesdays and Fridays:
2:00-3:15pm, 1131 SC
- **Web page**
<http://www.cs.uiuc.edu/class/cs598tar>



Primarily Paper Reading

- Check class webpage for reading list soon (no reading due this week).
- Divide into groups of up to 3 people (partner on projects and homework).
- Each group collectively will be required to read two to four papers per week (from a reading list) on the topic covered in class, and type a half-page to one page summary of the paper indicating:
 - The main contributions of the paper.
 - A critique (positive and/or negative) of this paper.
 - The points of strength (best things you liked about the paper).
 - The points of weakness (things you didn't like about the paper).
 - Opportunities for future work on the topic.
- Summaries of assigned research papers (one per group) are to be submitted to the instructor by e-mail by 9pm of the day before class. (Please include the words "598 SUMMARY" in the subject of the e-mail, and include the group members and title of the critiqued paper in the body.
- A discussion of the research topic will ensue in class.



Grading

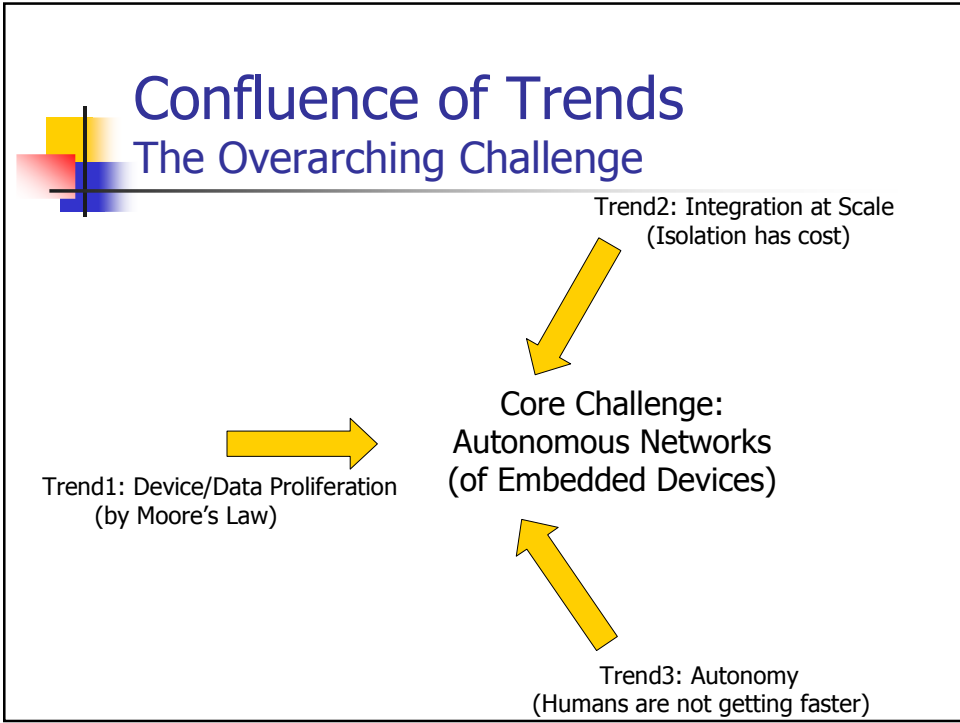
- **10%:** Class participation, and discussion of research papers.
- **10%:** Group summaries of the papers covered (all group members share the same grade). More credit will be given to groups with creative and original opinions, and on their ability to defend their correctness.
- **15%:** Open-book take-home midterm (out 3/14)
- **15%:** Open-book take-home final (out 5/2)
- **50%:** Substantial group course project.



Project

- **ASAP:** Find partners (a group of 3 is best)
- **2/8:** Submit project proposal (1 page)
- **3/12-3/14:** In class work-in-Progress presentation
- **4/25-4/30:** Final in-class presentation
- **5/2:** Final written report
- **Week of finals:** Project demo and discussion.

- Access will be provided to a project testbed in the second half of the semester.



Sensor "LANs"

Habitat Monitoring

Precision Agriculture

Disaster Response

Application Examples

Border Control

Miniaturization

- Constrained deployment
- Distribution at scale
- Interaction with a physical environment
- Unattended operation



CPS Networks

- Integration of
 - computation,
 - communication, and
 - interaction with the physical world



CPS Networks

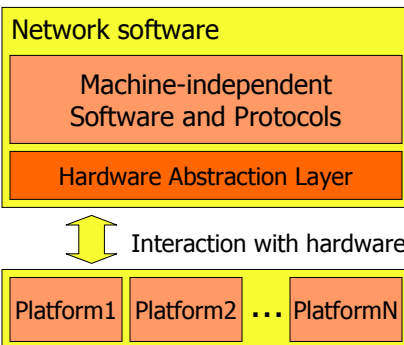
- Integration of
 - computation,
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Network Challenge – The “Adaptation” Layer

Auto-tuning of global properties

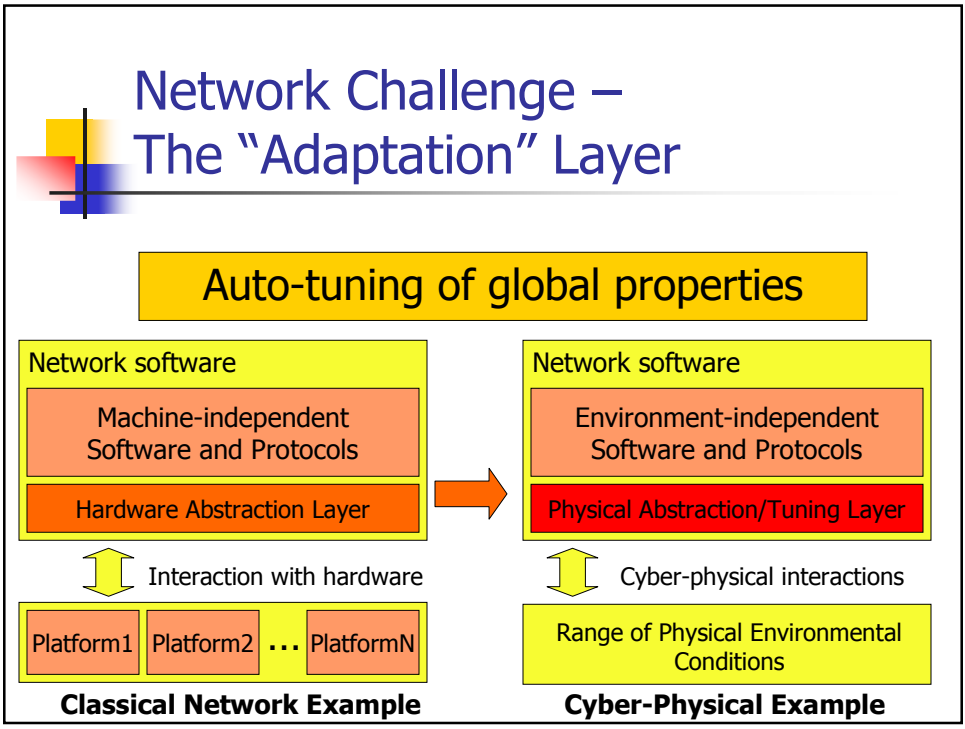
Network Challenge – The “Adaptation” Layer

Auto-tuning of global properties

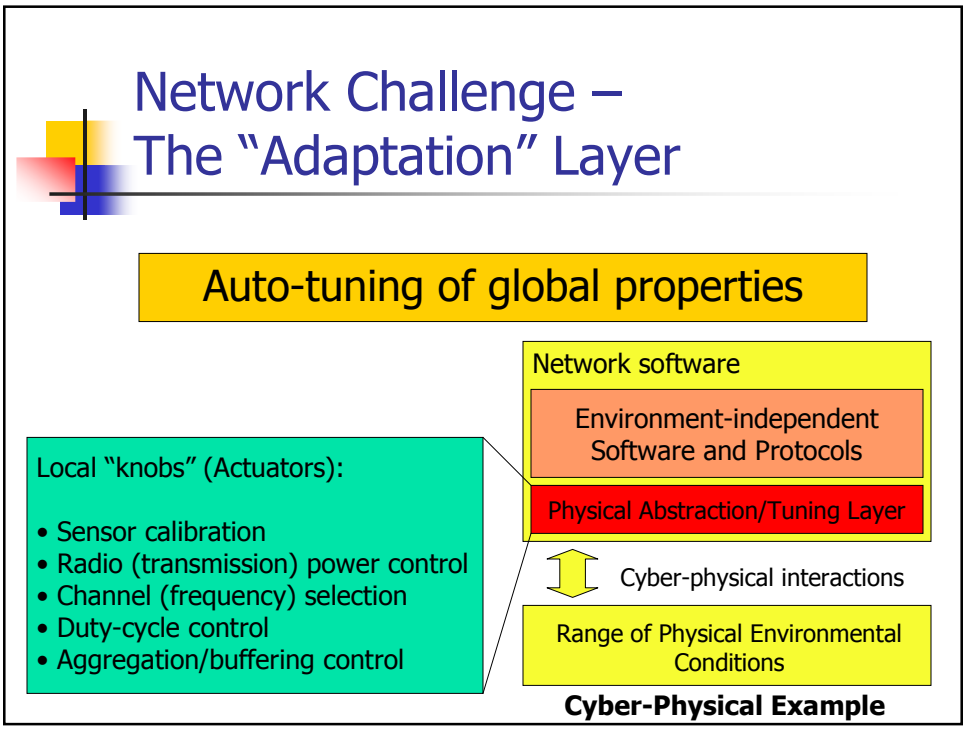


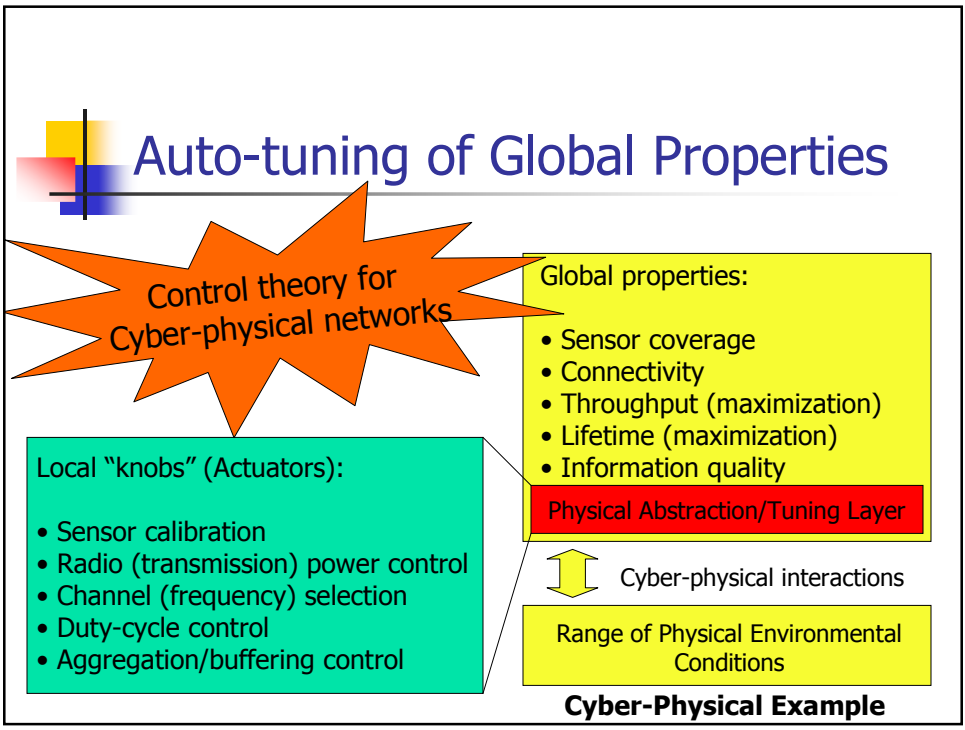
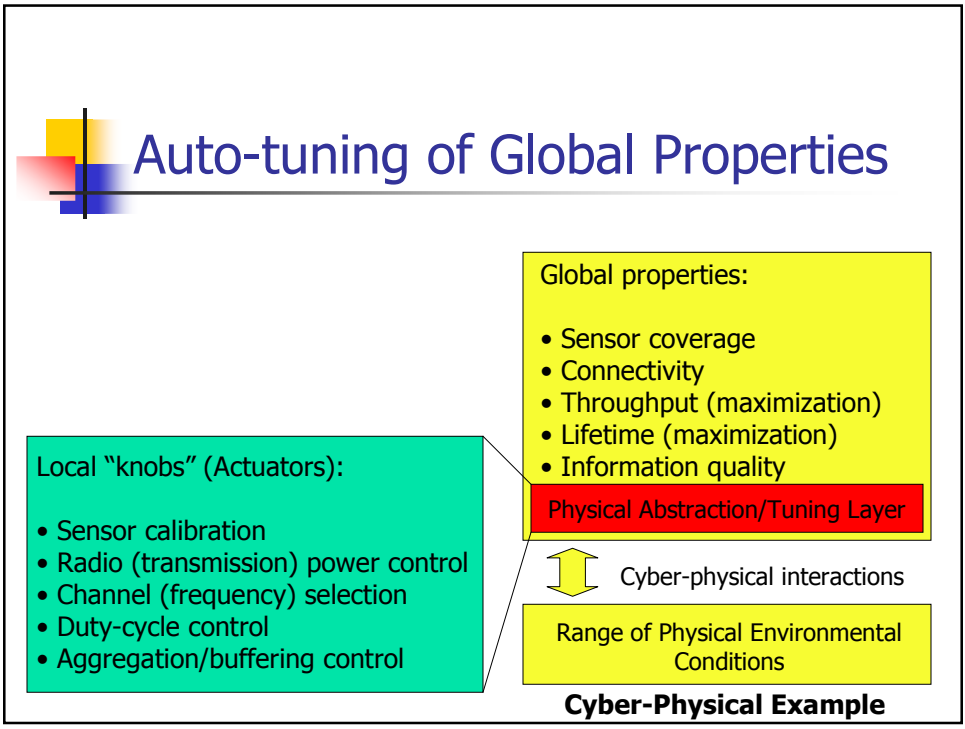
Classical Network Example

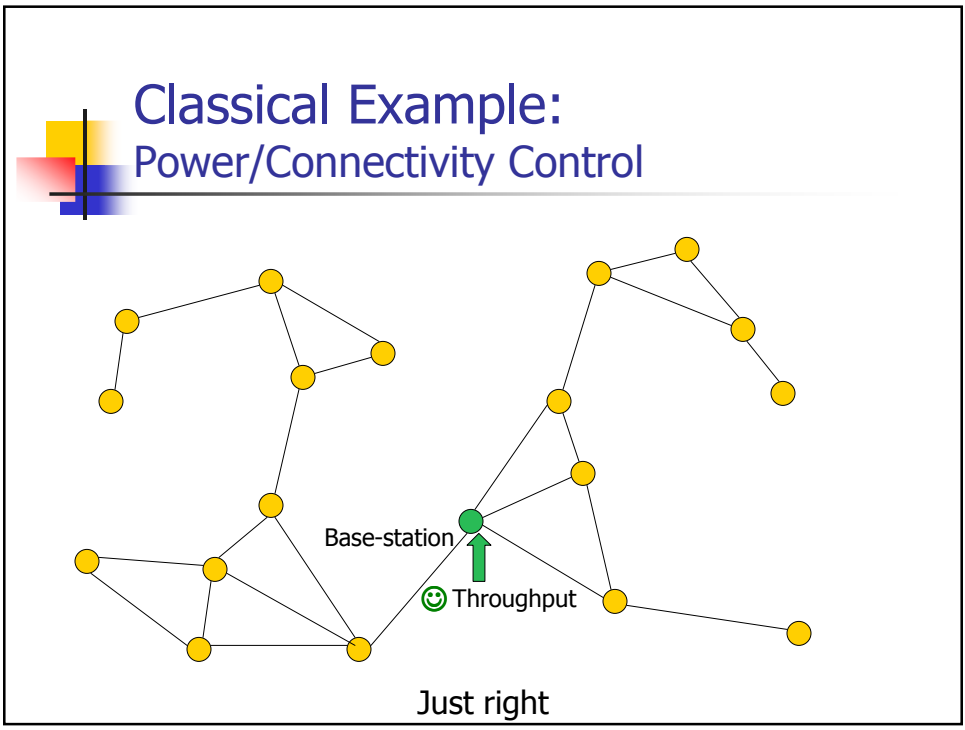
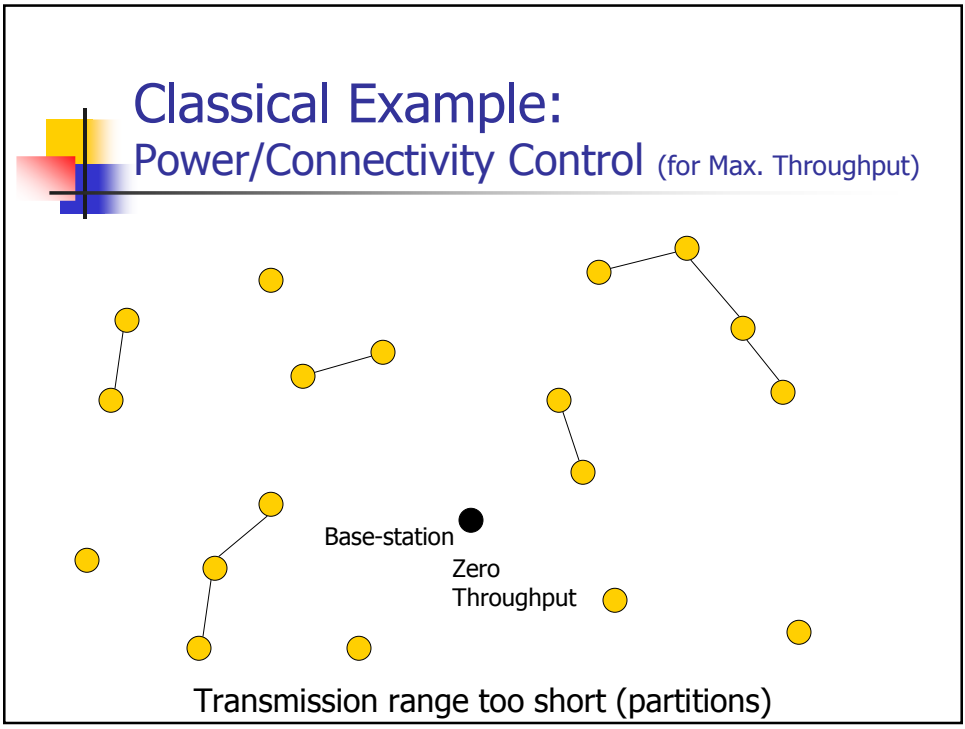
Network Challenge – The “Adaptation” Layer

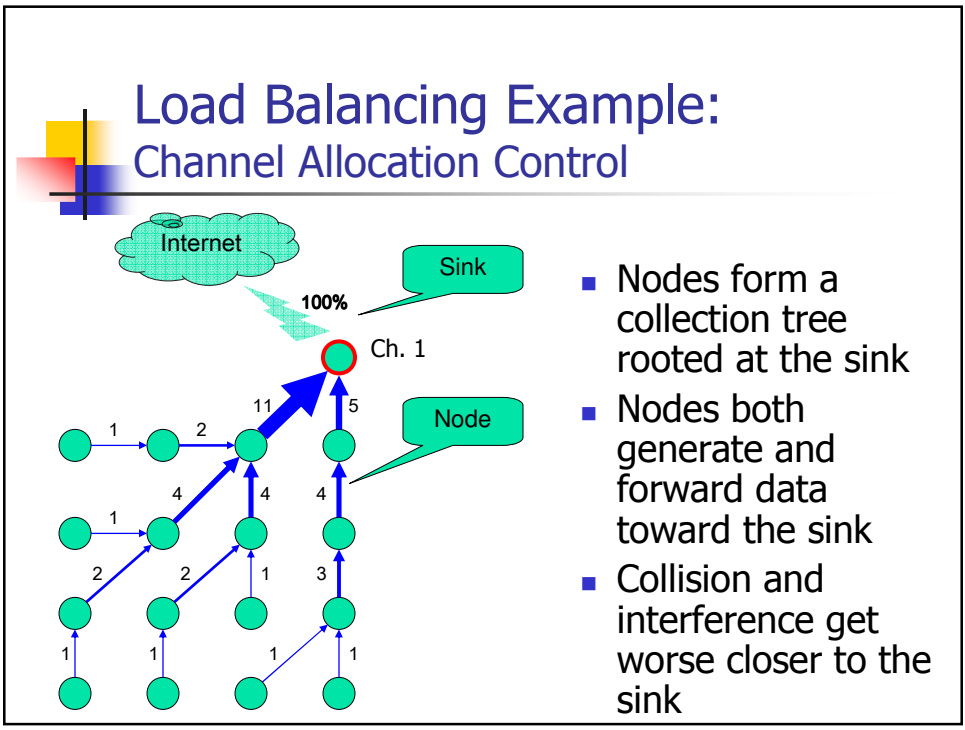
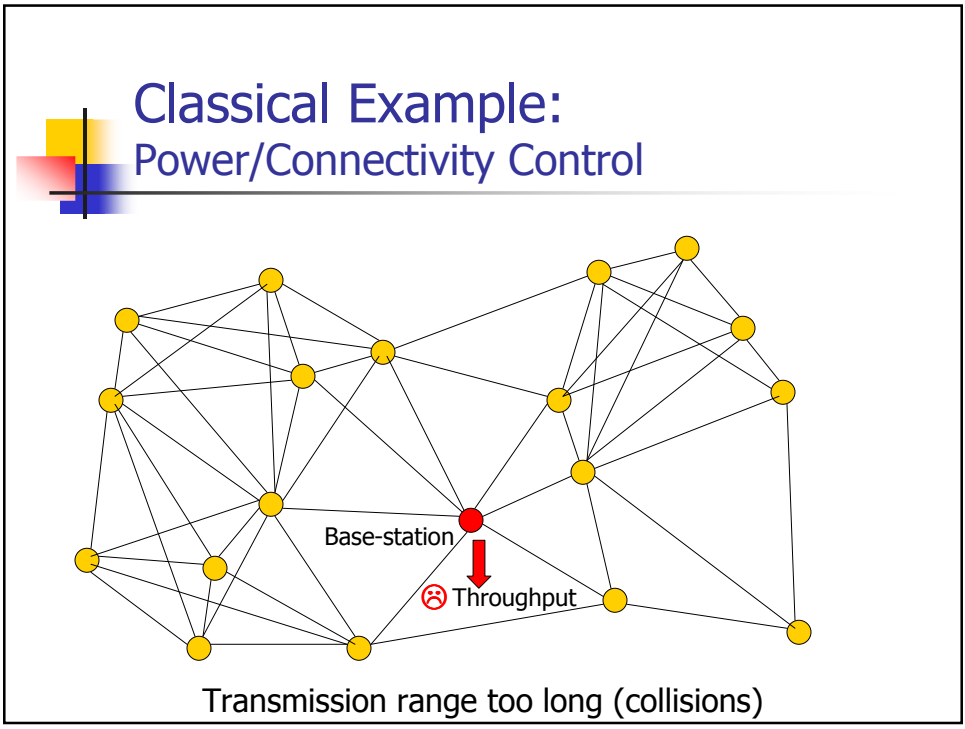


Network Challenge – The “Adaptation” Layer

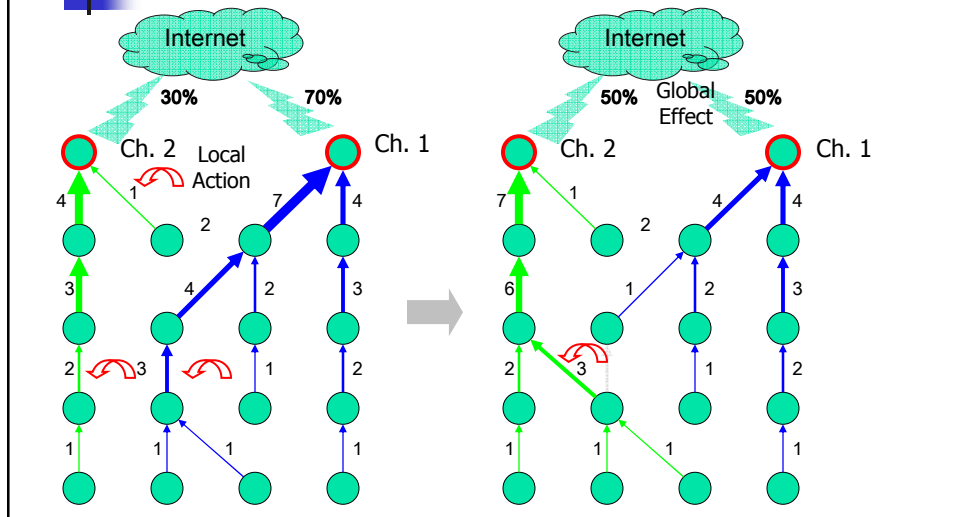




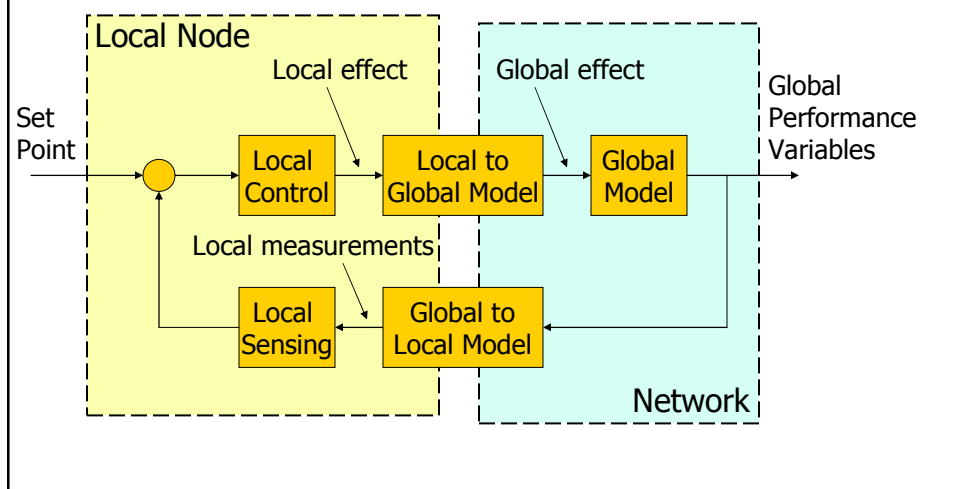




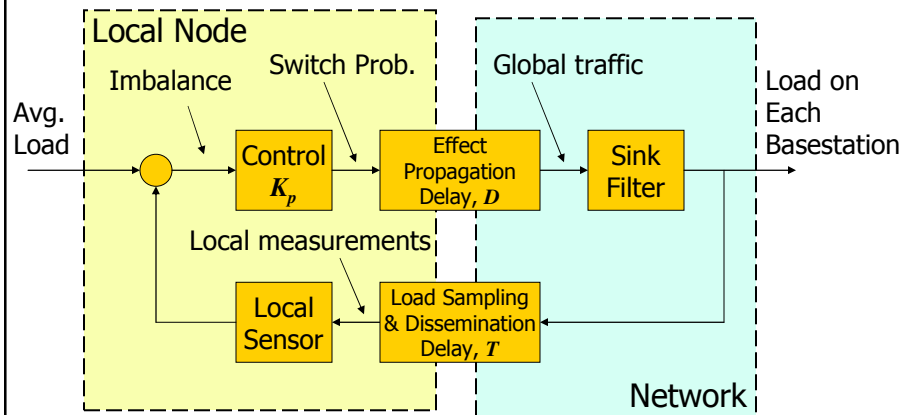
Load Balancing Example: Channel Allocation Control



A Simple Control-Theoretic Model of Adaptive Behavior



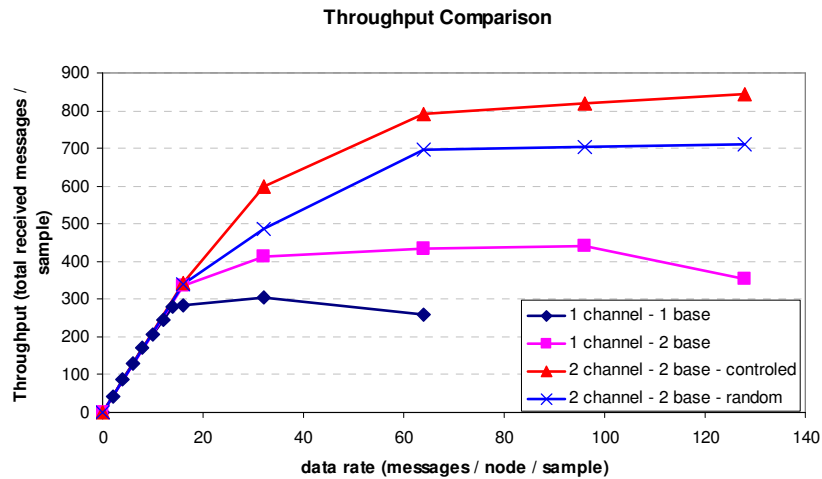
A Simple Control-Theoretic Model of Adaptive Behavior



Example: Control Testbed



Throughput Comparison with and without Automatic Control



General Challenge: Control of Global Network Behavior

- Sensor network protocols are localized; nodes act independently, locally, in response to local stimuli.
- How to argue about the global effects of such localized protocols when performed by all nodes?
- How to induce and analyze convergence to desired global properties?
- How to incorporate end-to-end time and total capacity constraints?
- Inspirations from control theory (convergence, stability), Markov decision theory (Markov chains, stochastic models), biology (behavior of social insects, swarm intelligence, bio-differentiation), physics (phase transitions, crystallization), ...



CPS Networks

- Integration of
 - computation,
 - communication, and
 - interaction with the physical world



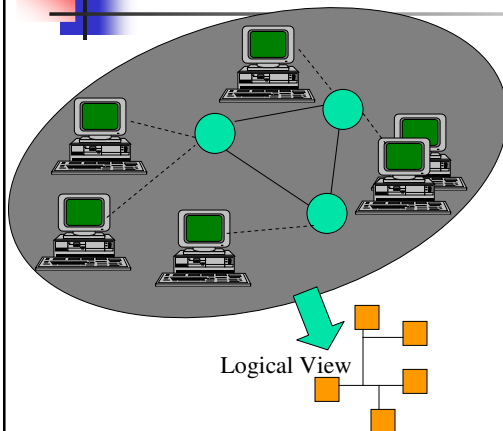
CPS Networks

- Integration of
 - **computation**,
 - **communication**, and
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Sensor Networks

- Integration of
 - computation,
 - communication, and
 - interaction with the physical world
- New Programming Paradigms
- Distributed Troubleshooting

Challenge: Distributed Programming Abstractions



- Distributed programming paradigms
 - Abstract distributed communication
 - Provide location transparency

Challenge: Distributed Programming Abstractions

The diagram on the left shows a network of five desktop computers connected to a central hub. A green arrow points from this network to a tree structure labeled 'Logical View'. The tree has a root node and three child nodes. To the right, a photograph of two soldiers in a field is overlaid with a sensor network diagram consisting of orange squares connected by dashed lines.

- Distributed programming paradigms**
 - Abstract distributed communication
 - Provide location transparency
- Sensor Network Programming Abstractions**
 - Represent the physical world to the programmer
 - Abstract distributed interaction with the physical environment

Architectures/Paradigms for In-network Computation

The diagram illustrates four programming paradigms for in-network computation. On the left, a 'Sensor network as a Database' is shown as a table with numerical data. In the center, 'Event based Paradigms' are represented by two nodes, A and B, with bidirectional arrows between them. On the bottom left, 'Node-based Programming' is shown as a cluster of blue dots. On the bottom right, 'Object-based Programming' is shown with a photograph of soldiers and a sensor network overlay.

	+2.000
0	+5.000
1	+1.500
0	+1.125
0	+1.062

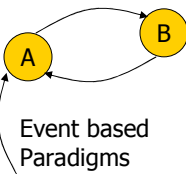
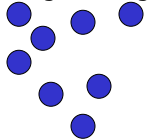
- Different paradigms for different applications
- Each supported by a black-box runtime system with a paradigm-specific API
- Can't mix and match

Architectures/Paradigms for In-network Computation

Sensor network as a Database

0	+2.888
0	+5.000
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Node-based Programming



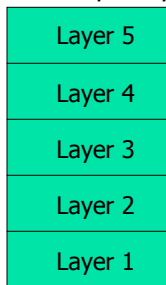
Event based Paradigms



Object-based Programming



- Contrast with networking
 - Layered abstractions
 - Different programmers can operate together at different layers
 - Programs can use APIs from multiple layers

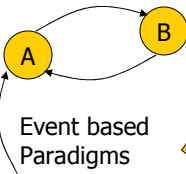
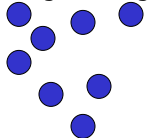


Layered (Network Protocols and) Programming Abstractions?

Sensor network as a Database

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Node-based Programming



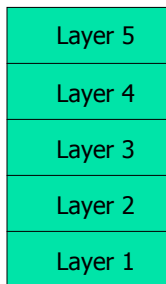
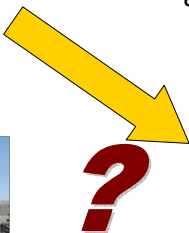
Event based Paradigms



Object-based Programming



- Towards a layered approach to programming abstractions?

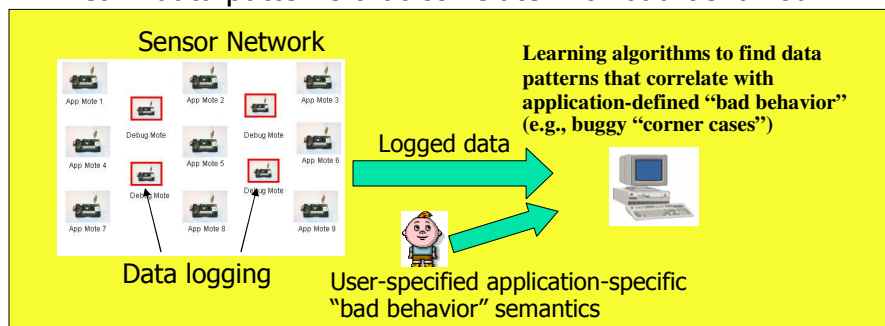


Challenge: Network Diagnosis and Troubleshooting Services

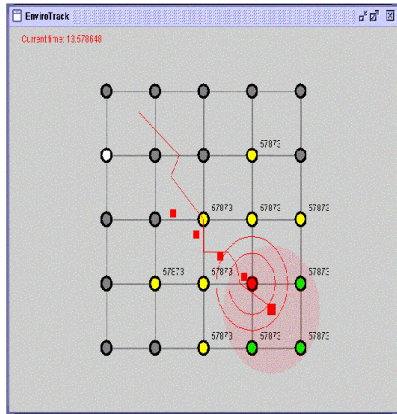
- Network performance problems and software bugs due of interaction among distributed components
 - Problems may not manifest themselves when testing individual components
 - Problems may appear to be non-repeatable

A Machine Learning Approach to Network Troubleshooting

- Monitor network state
- Label collected data into a “good pile” and a “bad pile” as defined by the user
- Learn data patterns that correlate with bad behaviour.



Case Study: Envirotrack

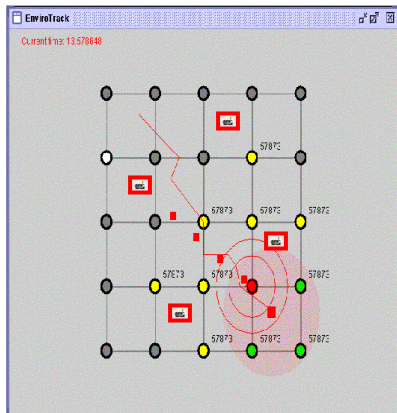


Envirotrack

- Distributed target tracking protocol (nodes that see target form group)
- Assigns unique ObjectID to each target
- Target movement causes leader handoff
- Sometimes hand-off failed resulting in more than one "detected target" for one physical target.
 - Why?

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Case Study: Envirotrack



Envirotrack

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Generated Results

- Leader handoff fails in singleton groups
 - **Uncovered bug: Singleton groups are not addressed**
- Holes in sensing coverage with slow target
 - **Violated assumption: 100% sensing coverage**

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A Future Network

might look something like this ...

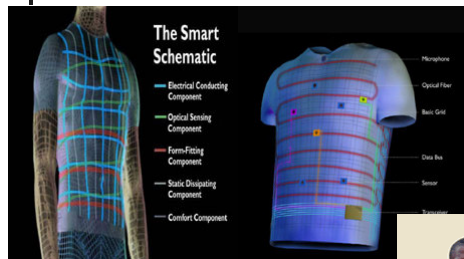


A Future Network might look something like this ...

Human-Centric Computing



Human-Centric Applications Empirical Evidence and Business case



<http://www.sensatex.com>

The master controller



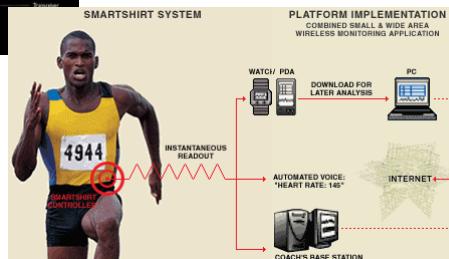
Nike -iPod



Spot



Wii



Technology introduced by 2007

Business Case? Health and Wellness

Health Vault



<http://www.sensatex.com>

The master controller



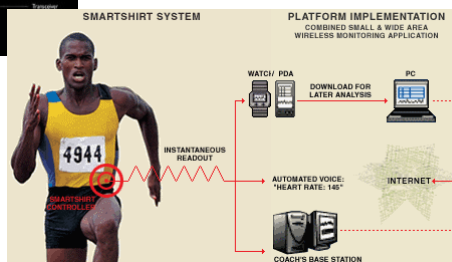
Nike -iPod



Spot



Wii



Business Case? Sports and Entertainment



<http://www.sensatex.com>

The master controller



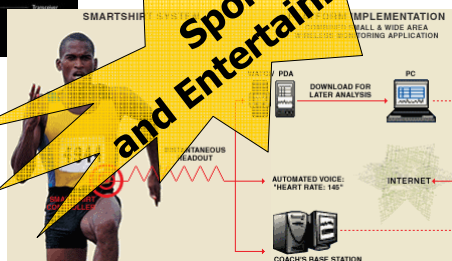
Nike -iPod



Spot



Wii



Business Case?

Multiplayer Games (beyond 2nd life)

Health and Wellness

Sports and Entertainment

Games

The master controller

Spot

The Smart Schematic

SMARTSHIRT IMPLEMENTATION

IMPLEMENTATION
SMALL & WIDE AREA
MONITORING APPLICATION

STAGNANT LAYOUT

AUTOMATED VOICE
"HEART RATE: 145"

INTERNET

COACH'S BASE STATION

DOWNLOAD FOR LATER ANALYSIS

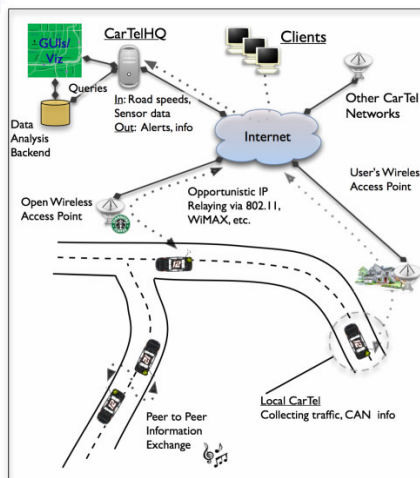
PDA

PC

<http://www.sensatex.com>

Community Application Example

CarTel (Sam Madden)



- An ad hoc network of vehicles with sensors
- Can measure road congestion
- Can generate maps of road conditions, etc.
- Given uncontrolled mobility model, how to perform global data operations (query dissemination, collection, etc)?

Reprinted from <http://cartel.csail.mit.edu/overview.html>



Challenge: Privacy Preserving Statistics

- A community of clients, each has a private data set S_i
- An information distillation service needs to compute some aggregate community quantity Q from the data sets S_i , $Q = f(S_1, S_2, \dots)$
- The problem statement: Perturb the private set S_i to generate the shareable set S'_i , such S_i cannot be recovered from S'_i but Q can still be (approximately) computed, $Q = f(S'_1, S'_2, \dots)$

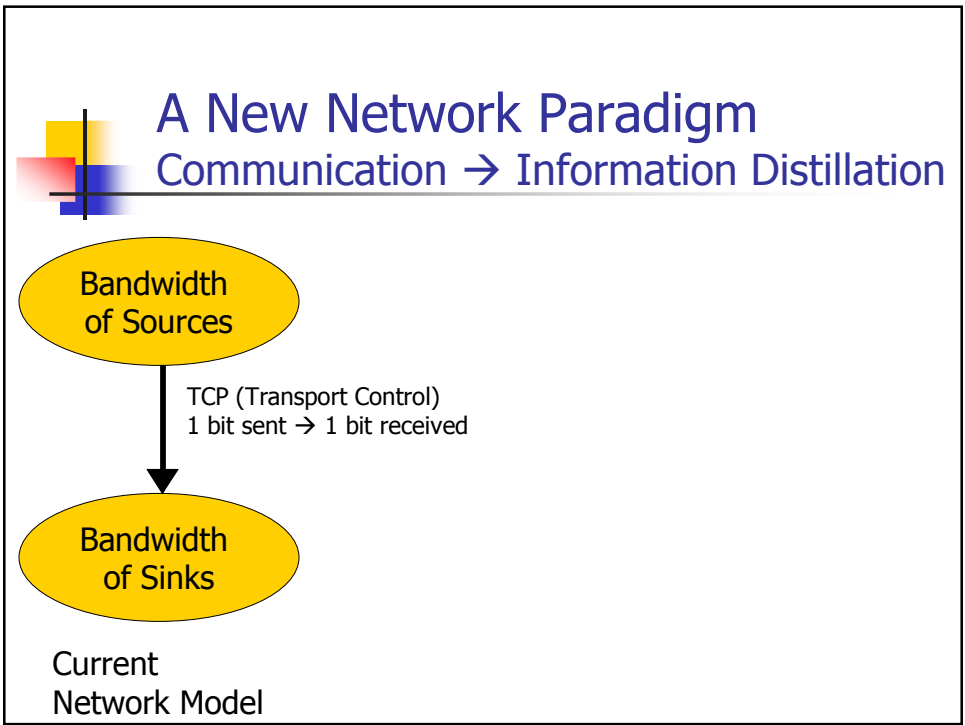


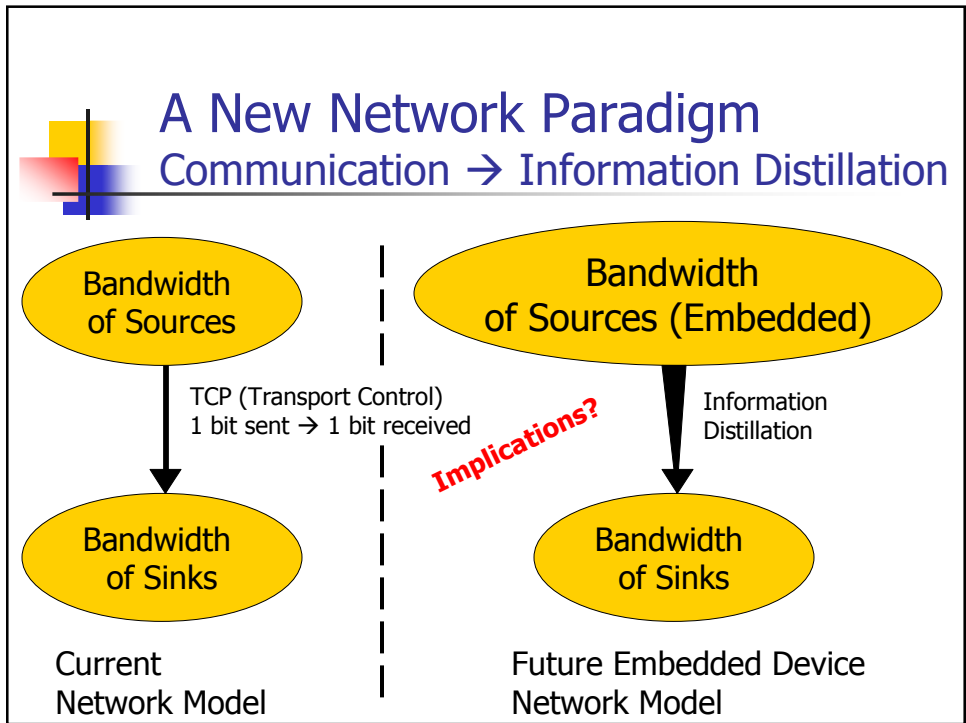
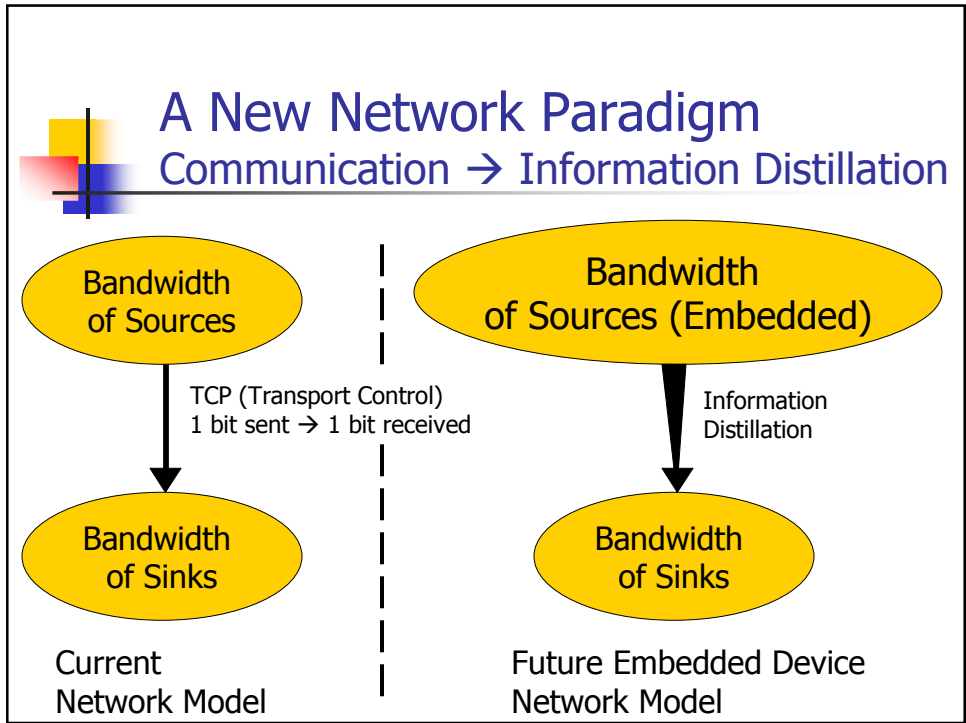
Challenge: Opportunistic Mobility and Disruption Tolerance

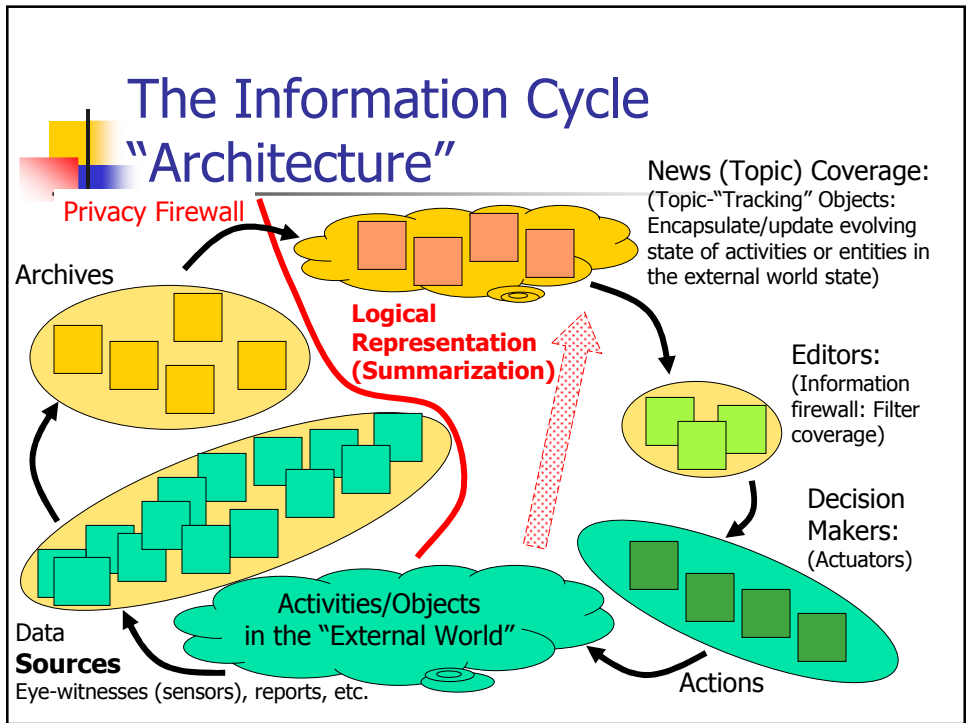
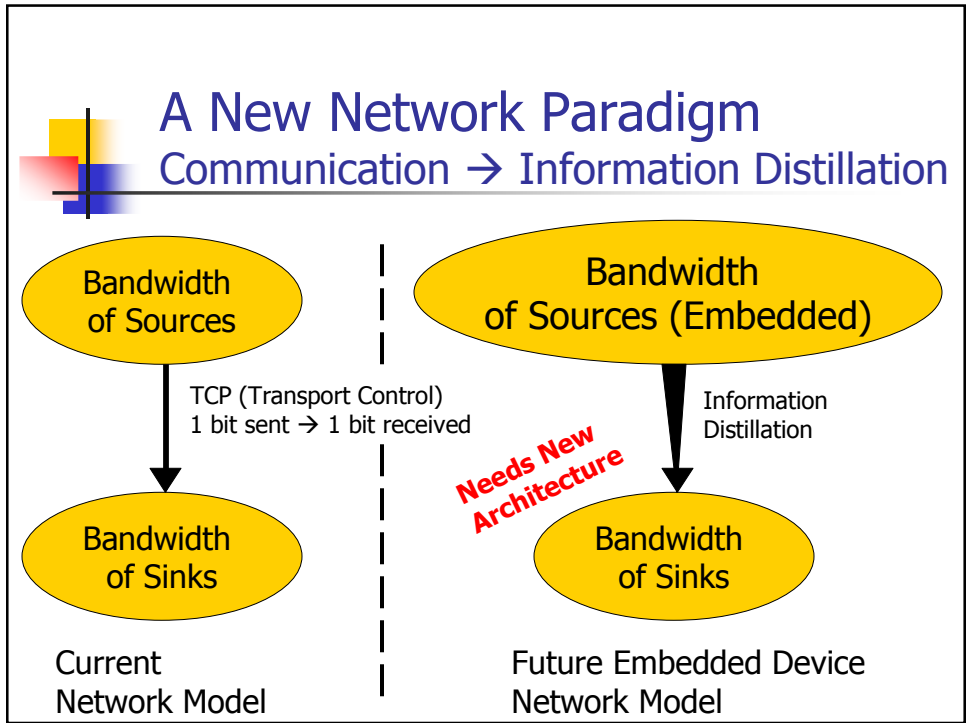
- Opportunistic (symbiotic or parasitic) mobility
 - The common case: mobile sensors that do not control their own mobility but follow motion of host (e.g., a GPS in a car)
 - Data hitchhiking: data have a destination - sensors copy data to devices that are "going in the right direction"
 - Host should benefit (symbiotic)
 - Examples: CarTel, SkiScape, ...
- External (phenomenon) mobility
 - Sensor mobility is determined by the measured object/phenomenon
 - Examples: cargo tracking, flow monitoring using floating sensors, etc.
- Scheduled mobility
 - Specialized device (robot, UAV, ...) acts as a data mule for a collection of static sensors

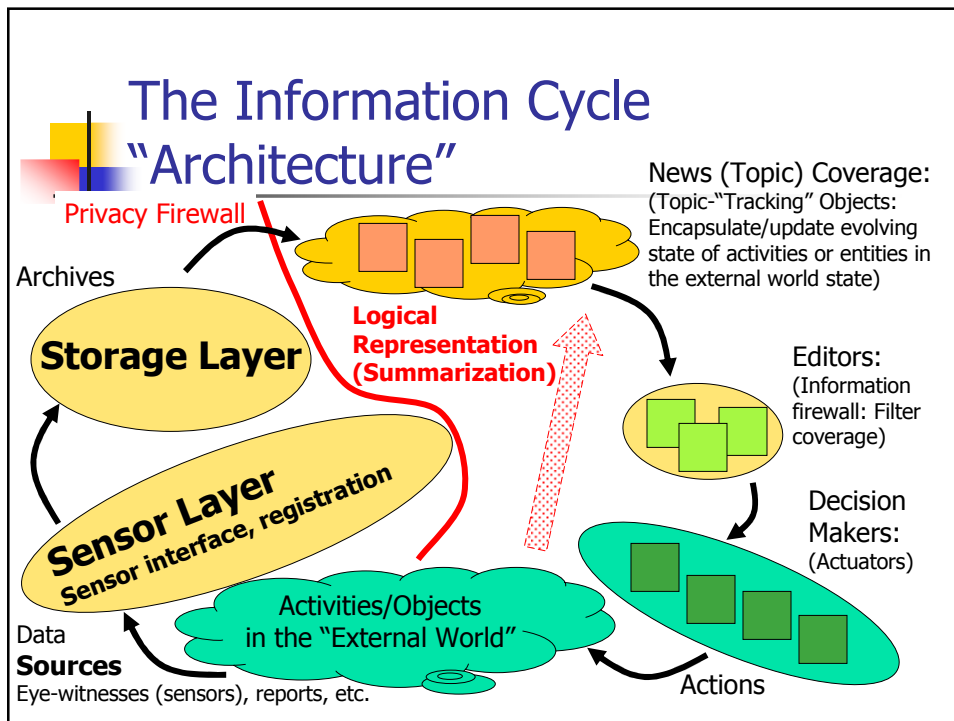
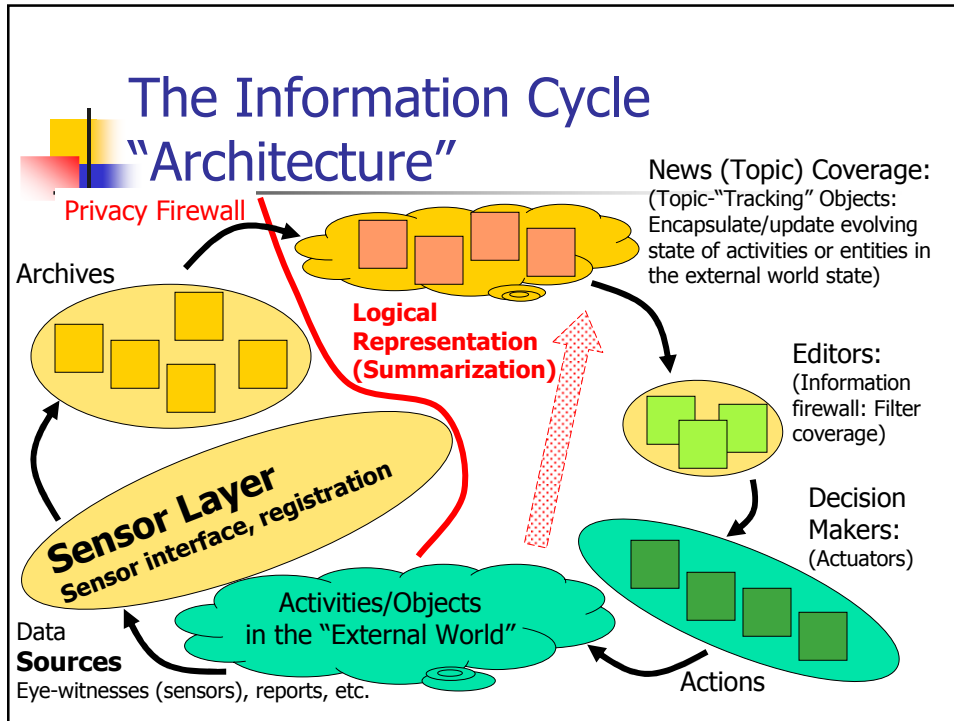
Eventually: A Network Paradigm Shift: Communication → Information Distillation

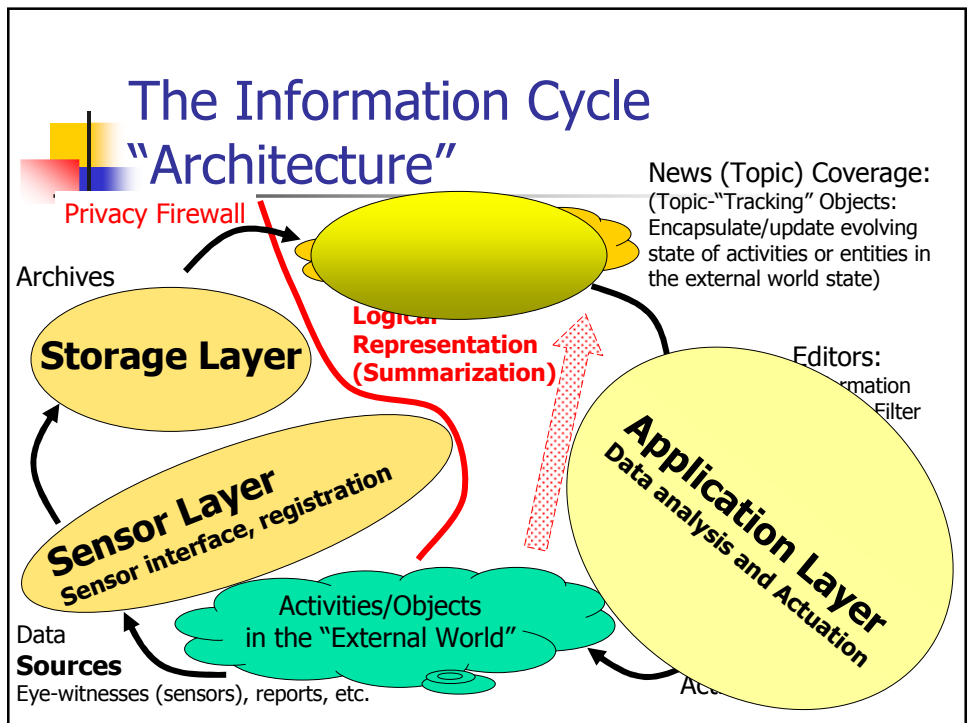
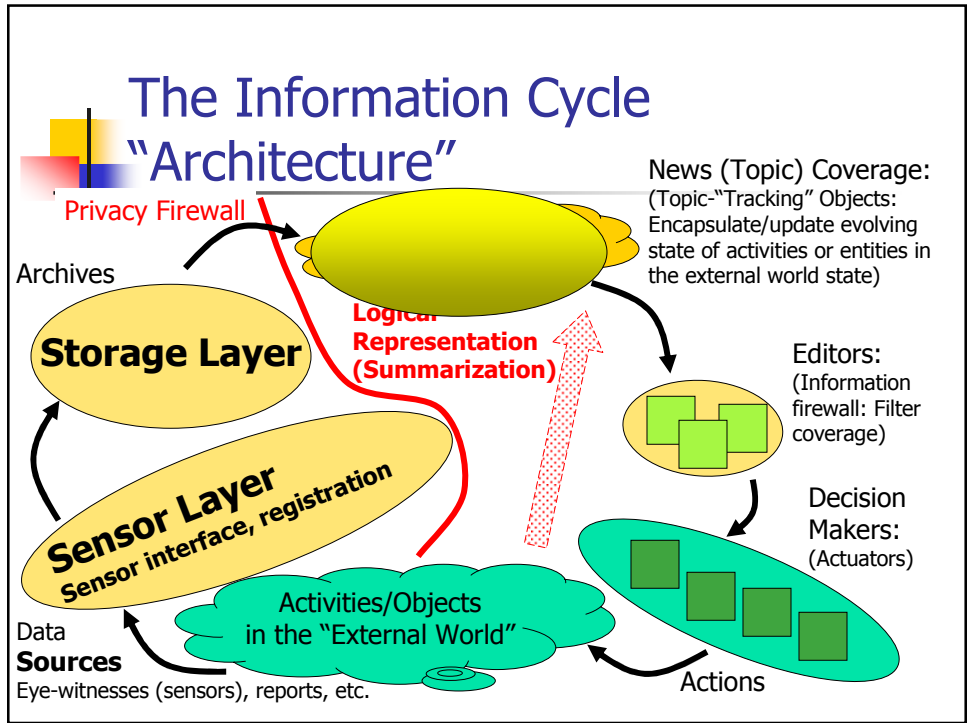
<ul style="list-style-type: none"> ■ Present Internet <p>Goal: Communication</p> <ul style="list-style-type: none"> ■ Connecting people ■ Protocols geared primarily for point-to-point communication ■ Data consumption applications: e-mail, VoIP, Web, P2P, ... 	<ul style="list-style-type: none"> ■ Future Embedded Device Nets <p>Goal: Information Distillation</p> <ul style="list-style-type: none"> ■ Reducing data from sensing inputs to actionable information <ul style="list-style-type: none"> ■ Human is out of the main data reduction loop ■ Protocols geared for data filtering, aggregation, mining, ... ■ Data reduction applications: Emergency detection/response, statistical community analysis, ...
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Where is the Thin Waist?



Where is the Thin Waist?

- Recall:
 - Communication → **Information Distillation**

- A Distillation Socket Layer?



Other Challenges

- Privacy! ... did I mention privacy??
- Mobility (opportunistic, symbiotic, parasitic, ...)
- Security (control of critical infrastructure?)
- Storage, indexing, archiving, ...
- Data analysis, statistical learning, data mining, ...
- Design for integration (large number of components breeds integration problems)
- Robustness (adaptation, self-healing, etc)
- Power management
- Performance analysis tools (capacity, availability, ...)