

CS 550: Iterative and Multigrid Methods  
Spring 2007

Homework, Set 1

Due Thursday February 22, 2007

*Write descriptive solutions. Comment your code!*

The goal of this homework set is to investigate the projection methods of chapters 4, 5, and part of 6. You should build off of the `splat` package developed in HW1. note: assume sorted CSR format.

1. `basicsolve.h` Implement efficiently weighed-Jacobi and Gauss-Seidel with the following prototypes

```
wJacobi(CSRMat *A, DVec *b, DVec *x, const int iter, const double omega);
GaussSeidel(CSRMat *A, DVec *b, DVec *x, const int iter);
// A x = b
// x      = initial guess and return vector
// A,b    = CSR matrix and rhs
// iter   = number of sweeps to perform
// omega  = weighed Jacobi parameter
```

2. Construct an example problem from FDIFF that compares the convergence of `wJacobi` versus `GaussSeidel`. A plot of iterations versus the (log) relative residual is useful.

3. `basicsolve.h` The recurrence

$$x_{k+1} = x_k + \alpha r_k$$

where  $\alpha \in \mathbb{R}$  is known as Richardson iteration. Implement Richardson with the following prototype

```
Richardson(CSRMat *A, DVec *b, DVec *x, const int iter, const double alpha
);
```

4. What polynomial  $p(A)$  at step  $m$  does Richardson Iteration correspond to?
5. (extra credit) Consider  $A = 2I_n + R$ , where  $R_{i,j} = 0.5/\sqrt{n} * \text{drand48}()$ . What choice of  $\alpha$  should be used? Consider  $B = A + D$  where  $D$  is diagonal and  $D_{kk} = (-2 + 2 \sin \theta_k) + i \cos \theta_k$  and  $\theta_k = \frac{k\pi}{m-1}$ , for  $0 \leq k \leq n-1$ . What choice of  $\alpha$  is needed here? Confirm your suspicions numerically.
6. `krylovsolve.h` Implement efficiently the GMRES algorithm outlined in class. Specifically, use the Arnoldi-MGS version of orthogonalization (versus Householder) and use Givens Rotations as described in section 6.5.3. Use the following prototype

```
GMRES(CSRMat *A, DVec *b, DVec *x,
      const int m, const double rtol, const int maxit,
      int &iter, DVec* res);
// A x = b
// x      = initial guess and return vector
// A,b    = CSR matrix and rhs
// m      = restart
// rtol   = relative residual stopping criteria
// maxit  = total number of iterations allowed (outer and inner)
// iter   = number of iterations needed to converge
// res    = residual history if not NULL
```

7. In class we attempted to bound the size of  $\|r_k\|_2$  and found a strong dependence on  $\kappa(T)$  (the deviation of  $A$ 's normality) and on the polynomial selected from the Krylov space. Consider the matrix  $A = TDT^{-1}$  with

$$D = \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \quad T = \begin{bmatrix} 1 & \beta & & \\ & \ddots & \ddots & \\ & & 1 & \beta \\ & & & 1 \end{bmatrix}$$

. For  $\beta = 0$ ,  $\kappa(T) = 1.0$  since the  $A$  is normal. Set  $\beta = 0.9$ . Investigate the following cases and describe your results. It will be helpful to generate log-linear plots of both residual history and residual reduction  $\|r_k\|_2/\|r_{k-1}\|_2$  versus iteration. Also, the Ritz values,  $\theta_i \in \Lambda(H_m)$  are useful but not necessary. Use an initial guess of 0 and  $b = Ax$ , where  $x = S\mathbf{1}$ .

(i) Initialize  $\lambda_j = j$ ,  $j = 1, \dots, n$ . Consider  $D(2, 2) = 1.0 + \alpha$  as  $\alpha \rightarrow 0$

(ii) Initialize  $\lambda_j = j$ ,  $j = 1, \dots, n$ . Consider  $D_{1:j,1} = J_j$ , where  $J_j$  a Jordan block of size  $j$  with a multiple eigenvalue of 1.0. Look at  $j$  increasing slightly.

8. Implement CG as described in algorithm 6.18. Consider a diagonal system ( $n = 100$ ) with the minimum diagonal entry to be 0.0005 and the rest to be evenly distributed in  $[0.08, 1.21]$ . Use  $x_0 = 0$  and  $b = 1$ . Investigate the behavior of CG. You may want to look at both the residual and the  $A$ -norm of the error.

```
CG(CSRMat *A, DVec *b, DVec *x,
    const double rtol, const int maxit, int &iter, DVec* res);
// A x = b
// x      = initial guess and return vector
// A,b    = CSR matrix and rhs
// rtol   = relative residual stopping criteria
// maxit  = total number of iterations allowed (outer and inner)
// iter   = number of iterations needed to converge
// res    = residual history if not NULL
```

9. Suppose  $A$  is a dense symmetric positive definite  $1000 \times 1000$  matrix with  $\kappa(A) = 100$ . Estimate the flops required to solve  $Ax = b$  to ten digits with Cholesky, Richardson with  $\alpha_{opt}$ , and with CG.

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CS550\_hw2\_L0lson

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tar xvfz CS550\_hw2\_L0lson.tgz

Comments or homework write-up should be included in this directory under hw2.pdf.