

IEEE 802.11, Token Rings

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Medium Access Control

- Wireless channel is a shared medium
- Need access control mechanism to avoid interference
- Why not CSMA/CD?

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Ethernet MAC Algorithm



- Listen for carrier sense before transmitting
- Collision: What you hear is not what you sent!

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CSMA/CD in WLANs?

- Most (if not all) radios are half-duplex
 - Listening while transmitting is not possible
- Collision might not occur at sender
 - Collision at receiver might not be detected by sender!

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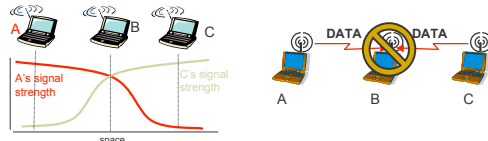
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Hidden Terminal Problem

- Node B can communicate with both A and C
- A and C cannot hear each other
- When A transmits to B, C cannot detect the transmission using the carrier sense mechanism
- If C transmits, collision will occur at node B



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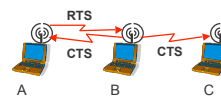
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MACA Solution for Hidden Terminal Problem

- When node A wants to send a packet to node B
 - Node A first sends a Request-to-Send (RTS) to A
- On receiving RTS
 - Node A responds by sending Clear-to-Send (CTS)
 - provided node A is able to receive the packet
- When a node C overhears a CTS, it keeps quiet for the duration of the transfer



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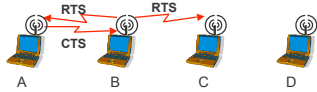
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Exposed Terminal Problem

- B talks to A
- C wants to talk to D
- C senses channel and finds it to be busy
- C stays quiet (when it could have ideally transmitted)



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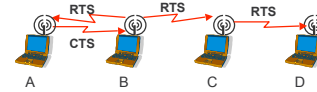
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MACA Solution for Exposed Terminal Problem

- Sender transmits Request to Send (RTS)
- Receiver replies with Clear to Send (CTS)
- Neighbors
 - See CTS - Stay quiet
 - See RTS, but no CTS - OK to transmit



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Collisions

- Still possible
 - RTS packets can collide!
- Binary exponential backoff
 - Backoff counter doubles after every collision and reset to minimum value after successful transmission
 - Performed by stations that experience RTS collisions
- RTS collisions not as bad as data collisions in CSMA
 - Since RTS packets are typically much smaller than DATA packets

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Reliability

- Wireless links are prone to errors
 - High packet loss rate detrimental to transport-layer performance
- Mechanisms needed to reduce packet loss rate experienced by upper layers

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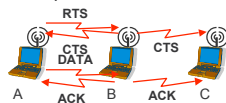
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A Simple Solution to Improve Reliability - MACAW

- When node B receives a data packet from node A, node B sends an Acknowledgement (ACK)
- If node A fails to receive an ACK
 - Retransmit the packet



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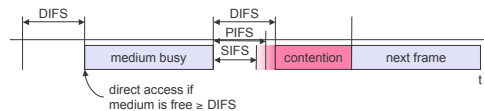
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Interframe Spacing

- Interframe spacing
 - Plays a large role in coordinating access to the transmission medium
- Varying interframe spacings
 - Creates different priority levels for different types of traffic!
- 802.11 uses 4 different interframe spacings



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IEEE 802.11 - CSMA/CA

- Sensing the medium
- If free for an Inter-Frame Space (IFS)
 - Station can start sending (IFS depends on service type)
- If busy
 - Station waits for a free IFS, then waits a random back-off time (collision avoidance, multiple of slot-time)
- If another station transmits during back-off time
 - The back-off timer stops (fairness)

The diagram illustrates the CSMA/CA process. It shows a timeline where a station senses the medium. If it is free for a DIFS (Distributed Inter-Frame Space), it can have direct access. If busy, it waits for a free IFS, then enters a contention window (randomized back-off mechanism) where it counts down in increments of slot time. If another station transmits during this back-off time, the timer stops. Once the window ends, the station transmits the next frame.

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Types of IFS

- SIFS
 - Short interframe space
 - Used for highest priority transmissions
 - RTS/CTS frames and ACKs
- DIFS
 - DCF interframe space
 - Minimum idle time for contention-based services (> SIFS)

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Types of IFS

- PIFS
 - PCF interframe space
 - Minimum idle time for contention-free service (>SIFS, <DIFS)
- EIFS
 - Extended interframe space
 - Used when there is an error in transmission

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Backoff Interval

- When transmitting a packet, choose a backoff interval in the range $[0, cw]$
 - cw is contention window
- Count down the backoff interval when medium is idle
 - Count-down is suspended if medium becomes busy
- When backoff interval reaches 0, transmit RTS

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DCF Example

The diagram shows two nodes, Node 1 and Node 2, with their backoff intervals and data transmissions. Node 1 starts with a backoff interval $B1 = 25$ (red bars), then a shorter interval $B1 = 5$ (red bars), and then transmits data (yellow bar). Node 2 starts with a backoff interval $B2 = 20$ (red bars), then a shorter interval $B2 = 15$ (red bars), transmits data (yellow bar), and then another interval $B2 = 10$ (red bars). The contention window $cw = 31$ is indicated. A note states: "B1 and B2 are backoff intervals at nodes 1 and 2".

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Backoff Interval

- The time spent counting down backoff intervals is a part of MAC overhead
- Large cw
 - Large backoff intervals
 - Can result in larger overhead
- Small cw
 - larger number of collisions (when two nodes count down to 0 simultaneously)

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Backoff Interval

- The number of nodes attempting to transmit simultaneously may change with time
 - Some mechanism to manage contention is needed
- IEEE 802.11 DCF
 - Contention window cw is chosen dynamically depending on collision occurrence

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Binary Exponential Backoff in DCF

- When a node fails to receive CTS in response to its RTS, it increases the contention window
 - cw is doubled (up to an upper bound)
- When a node successfully completes a data transfer, it restores cw to Cw_{min}
 - cw follows a sawtooth curve

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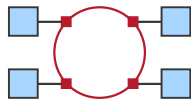
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Token Ring

- Example Token Ring Networks
 - IBM: 4Mbps token ring
 - IEEE 802.5: 16Mbps



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Token Ring

- Focus on Fiber Distributed Data Interface (FDDI)
 - 100 Mbps
 - Was (not is) a candidate to replace Ethernet
 - Used in some MAN backbones (LAN interconnects)
- Outline
 - Rationale
 - Topologies and components
 - MAC algorithm
 - Priority
 - Feedback
 - Token management

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Token Ring

- Why emulate a shared medium with point-to-point links?
- Why a shared medium?
 - Convenient broadcast capabilities
 - Switches costly
- Why emulation?
 - Simpler MAC algorithm
 - Fairer access arbitration
 - Fully digital (802.3 collision detection requires analog)

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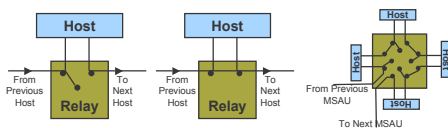
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Token Ring: Topology and Components

- Relay
 - Single Relay
 - Multistation access units



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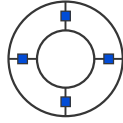
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Token Ring: Dual Ring

- Example Token Ring Networks
 - FDDI: 1000Mbps
 - Fiber Distributed Data Interface



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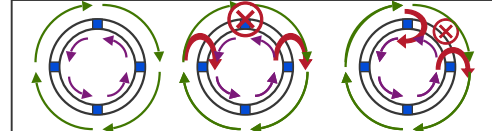
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FDDI

- Dual ring configuration
 - Self-healing
 - Normal flow in green direction
 - Can detect and recover from one failure



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Multistation Access Unit

- Each station imposes a delay
 - E.g. 50 ms
- Maximum of 500 Stations
- Upper limit of 100km
 - Need 200km of fiber
- Uses 4B/5B encoding
- Can be implemented over copper

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Token Ring: Basic Concepts

- Frames flow in one direction
 - Upstream to downstream
- Token
 - Special bit pattern rotates around ring
- Stations
 - Must capture token before transmitting
 - Must remove frame after it has cycled
 - Must release token after transmitting
- Service
 - Stations get round-robin service

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Token Ring: Basic Concepts

- Immediate release
 - Used in FDDI
 - Token follows last frame immediately
- Delayed release
 - Used in IEEE 802.5
 - Token sent after last frame returns to sender

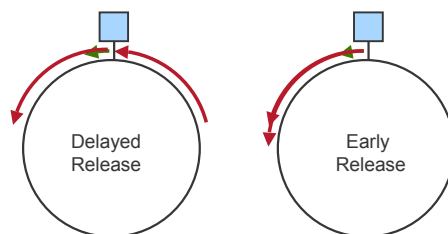
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Token Release



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Token Ring: Media Access Control Parameters

- Token Holding Time (THT)
 - Upper limit on how long a station can hold the token
 - Each station is responsible for ensuring that the transmission time for its packet will not exceed THT
- Token Rotation Time (TRT)
 - How long it takes the token to traverse the ring.
 - $TRT \leq \text{ActiveNodes} \times THT + \text{RingLatency}$
- Target Token Rotation Time (TTRT)
 - Agreed-upon upper bound on TRT

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802.5 Reliability

- Delivery status
 - Trailer
 - A bit
 - Set by recipient at start of reception
 - C bit
 - Set by recipient on completion on reception

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802.5 Monitor

- Responsible for
 - Inserting delay
 - Token presence
 - Should see a token at least once per TRT
 - Check for corrupted frames
 - Check for orphaned frames
 - Header
 - Monitor bit
 - Monitor station sets bit first time it sees packet
 - If monitor sees packet again, it discards packet

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Token Maintenance: 802.5

- Monitoring for a Valid Token
 - All stations should periodically see valid transmission (frame or token)
 - Maximum gap
 - = ring latency + max frame $\leq 2.5\text{ms}$
 - Set timer at 2.5ms
 - send claim frame if timer expires

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Timing Algorithm: 802.5

- Each node measures TRT between successive tokens
 - If measured-TRT > TTRT
 - Token is late
 - Don't send
 - If measured-TRT < TTRT
 - Token is early
 - OK to send
- Worse case:
 - $2 \times \text{TTRT}$ between seeing token
 - Back-to-back $2 \times \text{TTRT}$ rotations not possible

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Traffic Classes: FDDI

- Two classes of traffic
 - Synchronous
 - Real time traffic
 - Can always send
 - Asynchronous
 - Bulk data
 - Can send only if token is early

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Timing Algorithm: FDDI

- Each station is allocated S_i time units for synchronous traffic per TRT
- TTRT is negotiated
 - $S_1 + S_2 + \dots + S_N + \text{RingLatency} \leq \text{TTRT}$
- Algorithm Goal
 - Keep actual rotation time less than TTRT
 - Allow station i to send S_i units of synchronous traffic per TRT
 - Fairly allocate remaining capacity to asynchronous traffic
 - Regenerate token if lost

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Timing Algorithm: FDDI

- When a node gets the token
 - Set TRT = time since last token
 - Set THT = TTRT - TRT
 - If TRT > TTRT
 - Token is late
 - Send synchronous data
 - Don't send asynchronous data
 - If TRT < TTRT
 - Token is early
 - OK to send any data
 - Send synchronous data, adjust THT
 - If THT > 0, send asynchronous data

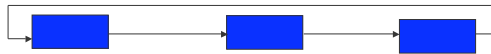
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FDDI example



- Assume
 - RingLatency=12 μ s
 - Three active stations
 - Each with $S_i=20 \mu$ s
 - TTRT=100 μ s
 - Stations have unlimited supply of asynchronous traffic.

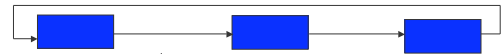
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FDDI example



Arrival time	TRT	s/a	Arrival time	TRT	s/a	Arrival time	TRT	s/a
0	0	0/0	4	0	0/0	8	0	0/0
12	12	20/88	124	120	20/0	148	140	20/0
172	160	20/0	196	72	20/28	248	100	20/0
272	100	20/0	296	100	20/0	320	72	20/28
344	100	20/0	396	100	20/0	420	100	20/0
444	72	20/28	496	100	20/0	520	100	20/0

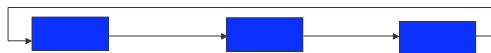
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FDDI example



0	0	0	0	0	0	0	0	0
12	12	88	124	120	0	148	140	0
172	160	0	196	72	28	248	100	0
272	100	0	296	100	0	320	72	28
372	100	0	396	100	0	420	100	0
444	72	28	496	100	0	520	100	0
544	100	0	568	72	28	620	100	0
644	100	0	668	100	0	692	72	28
744	100	0	768	100	0	792	100	0
816	72	28	868	100	0	892	100	0
916	100	0	940	72	28	992	100	0
1016	100	0	1040	100	0	1064	72	28
1116	100	0	1140	100	0	1164	100	0
1188	72	28	1240	100	0	1264	100	0
1288	100	0	1312	72	28	1364	100	0
1388	100	0	1412	100	0	1436	72	28
1488	100	0	1512	100	0	1536	100	0
1560	72	28	1612	100	0	1636	100	0
1660	100	0	1684	72	28	1736	100	0
1760	100	0	1784	100	0	1808	72	28

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FDDI Performance

- Synchronous traffic may consume one TTRT worth of time
 - TRT > TTRT
- Worst case
 - TRT < 2*TTRT
 - Any asynchronous traffic plus RingLatency \leq TTRT
 - Synchronous traffic < TTRT

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[FDDI Performance]

- Can't have two consecutive TRT = $2 \cdot TTRT$
 - After a cycle with TRT = $2 \cdot TTRT$, no asynchronous traffic will be sent

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[Token Maintenance: FDDI]

- Lost Token
 - No token when initializing ring
 - Bit error corrupts token pattern
 - Node holding token crashes
- Monitoring for a valid token
 - Should see valid transmission (frame or token) periodically – within $2 \cdot TTRT$
 - Maximum gap = RingLatency + MaxFrame \leq 2.5ms

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